

# Faculty of Engineering & Technology

### **Mechanical Mechanisms**

Information :

Course Code :	MAN 311	Level	:	Undergraduate	Course Hours :	3.00- Hours

**Department :** Department of Mechanical Engineering

### Instructor Information :

Title	Name	Office hours
Associate Professor	Hassan Mohamed Shams Eldin Elsayed Eleashy	8
Lecturer	Ahmed Sobhi Mohamed Gad	
Teaching Assistant	Eman Mohamed Hammad Ahmed	
Teaching Assistant	Eman Mohamed Hammad Ahmed	

### Area Of Study :

ÁPrepare student to analyze position, displacement, velocity and acceleration for planar mechanisms. ÁDevelop studentsaknowledge about different types of standard cams and equivalent mechanisms. ÁTrain student to perform force analysis of planar mechanisms, gear trains and applications to engine balancing machines.

## **Description**:

Kinematics Fundamentals: geometry of motion and mechanism topology, Linkage mechanisms and planar robots: position, displacement, velocity, and acceleration (Graphical, Analytical and Computers Assisted Methods), Camfollower mechanisms: design and analysis (Graphical, Analytical and Computers Assisted Methods), Standard cams and equivalent mechanisms, Kinematics of gear trains: gears terminology, simple, compound, and planetary gear trains, Dynamics fundamentals: force analysis of mechanisms, Applications to engine balancing machines, Applications and use of Computers for Mechanism Simulation and Animation.

### Course outcomes :

#### a.Knowledge and Understanding: :

-	-			
1 -	Define various parts involved in kinematics of machines for different applications.			
2 -	Identify requirements and the design aspects of basic machine elements.			
3 -	Describe different types of cams and followers.			
4 -	Estimates different methods to identify velocity, acceleration and force analysis of planar mechanisms.			
5 -	Define the fundamentals of the theory of kinematics and dynamics of machines			
b.Intellectual Skills: :				
1 -	Analyze various cam motion profiles and follower mechanism, their classification and design based on the prescribed follower motion.			
2 -	Construct different types of gear trains mechanisms.			
0	Evaluate the planer mode prime to evaluate the evictim former			

3 - Evaluate the planar mechanisms to overcome the existing forces.

http://www.fue.edu.eg



# c.Professional and Practical Skills: :

1 -	Prepare a schematic drawing of a real-world mechanism.		
2 -	Practice graphical methods to study the motion of a planar mechanism.		
3 -	Use computer software to study the motion of a mechanism.		
4 -	Demonstrate the common mechanisms used in machines and everyday life.		
5 -	Apply graphical and analytical techniques for analysis of different mechanism types.		
d.General and Transferable Skills: :			
1 -	Demonstrate efficient IT capabilities.		
2 -	Efficiently manage tasks, time and resources.		

## **Course Topic And Contents :**

Торіс	No. of hours	Lecture	Tutorial / Practical
Introduction to kinematics Fundamentals, Geometry of motion and mechanism topology, Linkage mechanisms and planar. robots	8	4	4
Velocity and acceleration analysis of any point on linkage for a plane motion.	12	6	6
Cam-follower mechanisms: design and analysis (Graphical, Analytical and Computers Assisted Methods).	10	6	4
Analysis of some standard cams and equivalent mechanisms.	10	4	6
Kinematics of gear trains: gears terminology, simple, compound, and planetary gear trains	8	4	4
Dynamics fundamentals: force analysis of mechanisms	4	2	2
Balancing of rotating masses.	4	2	2
Project follow -up.	4	2	2

# Teaching And Learning Methodologies :

Interactive Lecturing	
Problem solving	
Discussion	
Project	

<u>Course Assessment :</u>				
Methods of assessment	Relative weight %	Week No	Assess What	
Assignment	5.00			
Final Exam	40.00			
Mid- Exam 1I	15.00			
Mid- Exam I	15.00			
Participation	5.00			
Project	10.00			
Quizzes	10.00			



# Course Notes :

2. Lecture notes on the E-Learning Program (MOODLE), FUE Academic Advisor System.

### Recommended books :

Charles E. Wilson and J. Peter Sadler, % inematics and Dynamics of Machinery, SI Third Edition # Prentice Hall, ISBN: 0131866419, (2003)