An Analytical Inverse of the Jacobian Matrix of a Crane-Like Redundant Manipulator for Inverse Kinematics Solutions

Tarek Mohamed Mohamed Abdelrahman

Abstract

Proceedings of the IEEE International Workshop on Industrial Applications of Machine Vision and Machine Intelligence, Ropongi, Tokyo, Japan, February 2-4, pp.330-337

An Analytical Inverse of the Jacobian Matrix of a Crane-Like Redundant Manipulator for Inverse Kinematics Solutions 1987, January